$$\begin{split} \Delta x &= x_f - x_i & \text{for any scalar/vector in place of } x \\ \vec{d}_{ext} &= \vec{d}_i + \vec{d}_j & \text{Kinght's version for vector displacement} \\ \Delta \vec{x} &= \vec{x}_f - \vec{x}_i & \text{Carl's version for vector displacement} \\ u_x &= \frac{\Delta u}{\Delta t} & \text{definition of 1-D (instantions) velocity, take a slope of $v_i(t) \\ a_x &= \frac{\Delta u}{\Delta t} & \text{definition of acceleration, take a slope of $v_i(t) \\ \Delta x &= v_i \Delta t \leftrightarrow A = hw & \text{displacement serve under } \\ \Delta x &= v_i \Delta t \leftrightarrow A = hw & \text{displacement serve under } \\ \Delta x &= v_i \Delta t \leftrightarrow A = hw & \text{displacement serve under } \\ a_x &= \frac{\Delta u}{\Delta x} & \text{definition of acceleration due to } \\ a_y &= \alpha_x \Delta t \leftrightarrow A - hw & \text{displacement serve under } \\ a_x &= x_i + v_x \Delta t & \text{displacement are area under } \\ \alpha_x &= x_i + v_x \Delta t & \text{displacement area rea under } \\ x_f &= x_i + v_x \Delta t & \text{displacement area rea under } \\ x_f &= x_i + v_x \Delta t & \text{displacement area rea under } \\ (v_y)_f &= (v_y)_i + \frac{1}{2}\omega_x \Delta t & \text{displacement area rea under } \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{displacement area rea under } \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{displacement area rea under } \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{displacement area rea under } \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{dimentic formula for settar velocity} \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{dimentic formula for settar velocity} \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{dimentic formula for settar constant acceleration } \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{dimentic formula for settar constant acceleration} \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{dimentic formula for settar velocity} & p_y = y_x + (v_y)_y \Delta t - \frac{1}{2}g(\Delta t)^2 & p_y = -g \\ (v_y)_f &= (v_y)_i + \alpha_x \Delta t & \text{dimentic formula for settar velocity} \\ a_y &= -g & -9.80 \text{ m/s}^3 & \text{fres-fill acceleration} \\ a_y &= -g & -9.80 \text{ m/s}^3 & \text{fres-fill acceleration due to gravity} \\ x = \frac{2\pi}{4} = \frac{2\pi}{4} & \text{displacement vector for getar displacement} \\ \vec{x}^2 &= \alpha^2 + i^2 - 2abcc_x(C) & \text{poise if is formula} \\ \vec{x}^2 &= \alpha^2 + i^2 - 2abcc_x(C) & \text{poise if for sets to side c opposite \\ \vec{x}^2 &= \alpha^2 + i^$$$$

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These formulas are for magnitudes of forces. You need to consider the details of the problem to get the directions and eventually the correct signs in equations like $F_{x,\text{net}} = F_{x1} + F_{x2} + \dots$

$w_{\mathrm{apparent}} = m(g + a_y)$	apparent weight
$n = w_{yR} = mg\cos\theta$	magnitude of normal force for a ramp
$f_{\rm s,max}=\mu_s n$	magnitude of maximum static friction
$f_k = \mu_k n$	magnitude of kinetic friction \vec{f}_k is opposite to direction of \vec{v}
$f_r = \mu_r n$	rolling friction
$D = \frac{1}{2}C_D\rho Av^2$	empircal law for drag force in air