

# CS 240: Data Structures and Data Management

## Module 8 Study Guide

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### Key Concepts

- **Multi-dimensional data** consists of a collection of  $d$ -dimensional items with  $d$  aspects/coordinates.
- For  $d = 1$ , performing a **range search** is straightforward.
  - 1D range search in an ordered array —  $O(\log(n) + k)$
  - 1D range search in a binary search tree —  $O(\log(n) + k)$
- For  $d > 1$ , however, these methods do not scale easily.
- Instead, we use new data structures (based on trees) to store and search higher-dimensional data.
- **Quadtrees** partition a region of 2D points into equally-sized quadrants.
  - Construction —  $\Theta(nh)$
  - Range search —  $\Theta(nh)$
- **kd-trees** partition a region of 2D points based on the median point of each partition.
  - Construction —  $O(n \log(n))$
  - Range search —  $O(n^{1-1/d} + k)$
- **Range trees** are a “tree of trees”;  $x$ - and  $y$ -coordinates of each 2D point are stored in their own tree
  - Construction —  $O(n(\log(n))^{d-1})$
  - Range search —  $O((\log(n))^d + k)$

### Suggested Readings

- **Goodrich/Tamassia:** 12.1 (Range Trees), 12.3 (Quadtrees and  $k$ -D Trees)

## Practice Questions

### Goodrich/Tamassia

- R-12.8. What would be the worst-case space usage of a range tree, if the primary structure were not required to have  $O(\log(n))$  height?
- R-12.12. What is the worst-case depth of a  $k$ -d tree defined on  $n$  points in the plane? What about in higher dimensions?
- R-12.13. Suppose a set  $S$  contains  $n$  two-dimensional points whose coordinates are all integers in the range  $[0..N]$ . What is the worst-case depth of a quadtree defined on  $S$ ?
- R-12.14. Draw a quadtree for the following set of points, assuming a  $16 \times 16$  bounding box:
- $$\{(1, 2), (4, 10), (14, 3), (6, 6), (3, 15), (2, 2), (3, 12), (9, 4), (12, 14)\}.$$
- R-12.15. Construct a  $k$ -d tree for the point set of Exercise R-12.14.
- C-12.2. Give a pseudocode description of an algorithm for constructing a range tree from a set of  $n$  points in the plane in  $O(n \log(n))$  time.
- C-12.4. Design a static data structure (which does not support insertions and deletions) that stores a two-dimensional set  $S$  of  $n$  points and can answer queries of the form  $\text{COUNTALLINRANGE}(a, b, c, d)$  in  $O(\log^2(n))$  time, which returns the number of points in  $S$  with  $x$ -coordinates in the range  $[a..b]$  and  $y$ -coordinates in the range  $[c..d]$ . What is the space used by this structure?
- C-12.5. Design a data structure for answering  $\text{COUNTALLINRANGE}$  queries (as defined in the previous exercise) in  $O(\log(n))$  time.  
(*Hint*: Think of storing auxiliary structures at each node that are “linked” to the structures at neighbouring nodes.)
- C-12.6. Show how to extend the two-dimensional range tree so as to answer  $d$ -dimensional range-searching queries in  $O(\log^d(n))$  time for a set of  $d$ -dimensional points, where  $d \geq 2$  is a constant.  
(*Hint*: Design a recursive data structure that builds a  $d$ -dimensional structure using  $(d - 1)$ -dimensional structures.)